



± 2 g Tri-Axis Analog Specifications

PART NUMBER:

KXPC4-2050
Rev –
Aug 07

36 Thornwood Drive
Ithaca, New York 14850
Tel: 607-257-1080
Fax: 607-257-1146
www.kionix.com

| APPROVED BY | | DATE |
|-------------|-----------|--------|
| PROD. MGR. | S. Miller | 8/6/07 |
| TECH. MGR. | K. Foust | 8/6/07 |
| TEST MGR. | J. Chong | 8/6/07 |
| VP ENG. | T. Davis | 8/6/07 |

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| | | - | | Initial Release | 8/6/07 | |
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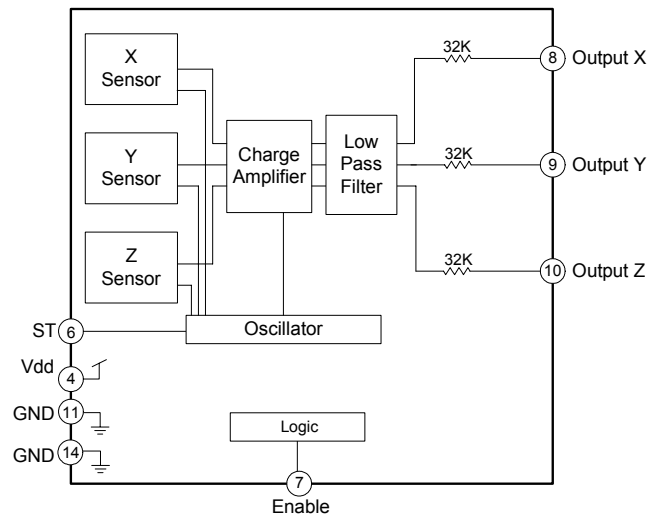
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Product Description

The KXPC4-2050 is a tri-axis, analog output, silicon micromachined accelerometer with a full-scale output range of $\pm 2g$ (19.6 m/s^2). The sense element is fabricated using Kionix's proprietary plasma micromachining process technology. Acceleration sensing is based on the principle of a differential capacitance arising from acceleration-induced motion of the sense element, which further utilizes common mode cancellation to decrease errors from process variation, temperature, and environmental stress. The sense element is hermetically sealed at the wafer level by bonding a second silicon lid wafer to the device using a glass frit. A separate ASIC device packaged with the sense element provides signal conditioning and self-test. The accelerometer is delivered in an 5 x 5 x 1.2mm Dual Flat No-lead (DFN) plastic package operating from a 1.8 - 5V DC supply.

Functional Diagram





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Product Specifications

Table 1. Mechanical

(specifications are for operation at $V_{dd} = 3.3V$ and $T = 25^{\circ}C$ unless stated otherwise)

| Parameters | Units | Min | Typical | Max |
|---|---------------------|---------------------|-----------------------|---------------------|
| Operating Temperature Range | $^{\circ}C$ | -40 | - | 85 |
| Zero-g Offset | V | 1.55 | 1.65 | 1.75 |
| Zero-g Offset Variation from RT over Temp. | $mg/^{\circ}C$ | | ± 1.0 | |
| Sensitivity | mV/g | 640 | 660 | 680 |
| Sensitivity Variation from RT over Temp. | $\%/^{\circ}C$ | | ± 0.015 | |
| Offset Ratiometric Error ($V_{dd} = 3.3V \pm 5\%$) | % | | 0.3 | |
| Sensitivity Ratiometric Error ($V_{dd} = 3.3V \pm 5\%$) | % | | 0.5 | |
| Non-Linearity | % of FS | | 1.5 | |
| Cross Axis Sensitivity | % | | 2.0 | |
| Self Test Output change on Activation | g | 1.6 (xy) 0.4 (z) | 2.0 (xy) 0.7 (z) | 2.4 (xy) 1.0 (z) |
| Mechanical Resonance (-3dB) ¹ | Hz | | 3300 (xy) 1700 (z) | |
| Noise Density (on filter pins) | $\mu g / \sqrt{Hz}$ | | 100 | |

Notes:

1. Resonance as defined by the damped mechanical sensor.

Table 2. Electrical

(specifications are for operation at $V_{dd} = 3.3V$ and $T = 25^{\circ}C$ unless stated otherwise)

| Parameters | Units | Min | Typical | Max | |
|--|-----------|---------|---------|-----|-----|
| Supply Voltage (V_{dd}) | Operating | V | 1.8 | 3.3 | 3.6 |
| Current Consumption | Operating | μA | 195 | 235 | 275 |
| | Standby | nA | - | - | 100 |
| Analog Output Resistance (R_{out}) | $k\Omega$ | 24 | 32 | 40 | |
| Power Up Time ¹ | ms | - | 16 | - | |
| Bandwidth (-3dB) ² | Hz | 40 | 50 | 60 | |

Notes:

1. For default filter frequency. Power up time can also be determined by 5 times the RC time constant of the optional user defined low pass filter.
2. Factory programmable. 50Hz is default.

| | | |
|---|---|---|
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Table 3. Environmental

| Parameters | | Units | Min | Typical | Max |
|-------------------------------------|-----------------|-------|------|---------|----------------|
| Supply Voltage (V _{dd}) | Absolute Limits | V | -0.3 | - | 6.0 |
| Operating Temperature Range | | °C | -40 | - | 85 |
| Storage Temperature Range | | °C | -55 | - | 150 |
| Mech. Shock (powered and unpowered) | | g | - | - | 5000 for 0.5ms |
| ESD | HBM | V | - | - | 2000 |

CAUTION:
ELECTROSTATIC
SENSITIVE COMPONENT



Caution: ESD Sensitive and Mechanical Shock Sensitive Component, improper handling can cause permanent damage to the device.

The 14-pin DFN package conforms to European Union Directive 2002/95/EC on the restriction of the use of certain hazardous substances in electrical and electronic equipment (RoHS).

Soldering

Soldering recommendations available upon request or from www.kionix.com.



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Application Schematic

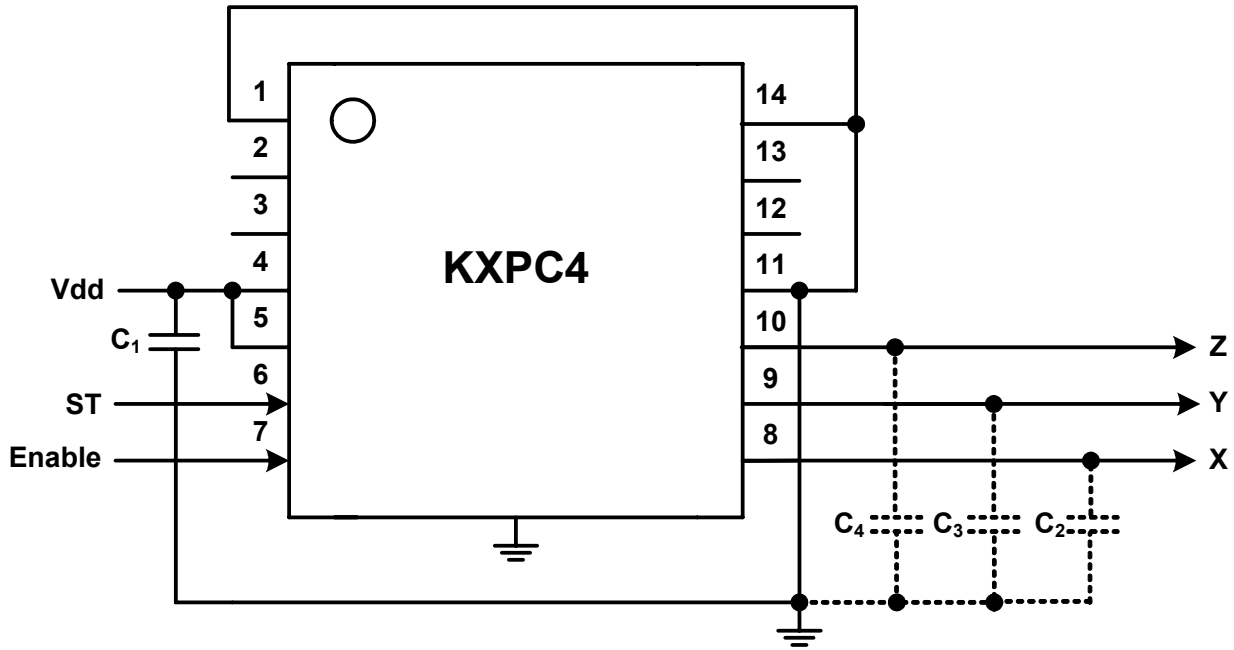


Table 4. KXPC4 Pin Descriptions

| Pin | Name | Description |
|-----|------------|---|
| 1 | GND | Ground |
| 2 | NC | Not Connected Internally |
| 3 | NC | Not Connected Internally |
| 4 | Vdd | The power supply input. Decouple this pin to ground with a 0.1µF ceramic capacitor (C ₁). |
| 5 | SDA | Pin must be held at Vdd for normal operation. |
| 6 | ST | Self Test: Low – Normal operation; High – Device is in self-test mode. |
| 7 | Enable | Enable pin: High - Normal operation; Low - Device is in standby, power down mode |
| 8 | X Output | Analog output of the x-channel (Optional filter capacitor, C ₂ shown). |
| 9 | Y Output | Analog output of y-channel (Optional filter capacitor, C ₃ shown). |
| 10 | Z Output | Analog output of z-channel (Optional filter capacitor, C ₄ shown). |
| 11 | GND | Ground |
| 12 | NC | Not Connected Internally |
| 13 | NC | Not Connected Internally |
| 14 | GND | Ground |
| | Center Pad | Ground |

| | | |
|---|---|---|
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Application Design Equations

The bandwidth is determined by a factory programmable switched capacitor filter. The default setting is 50Hz. Alternatively, bandwidth can be reduced by addition of a capacitor on the output pins 8, 9, and 10 according to the equation:

$$C_2 = C_3 = C_4 = \frac{4.97 \times 10^{-6}}{f_{BW}}$$

Note:

When the enable pin is connected to GND or left floating, the KXPC4 is in low power mode. When the enable pin is tied to Vdd, the unit is fully functional.

Test Specifications

! Special Characteristics:

These characteristics have been identified as being critical to the customer. Every part is tested to verify its conformance to specification prior to shipment.

Table 5. Test Specifications

| Parameter | Specification | Test Conditions |
|---------------------|---------------|------------------------------------|
| Zero-g Offset @ RT | 1.65 ± 0.10 V | 25°C, V _{dd} = 3.3V |
| Sensitivity @ RT | 660 ± 20 mV/g | 25°C, V _{dd} = 3.3V |
| Current Consumption | Operating | 0.195 ≤ I _{dd} ≤ 0.275 mA |
| | | 25°C, V _{dd} = 3.3V |

All specifications in Tables 1, 2, and 3 which are not listed in Table 5 (above) are tested on an audit or validation basis only and are not guaranteed to be within the minimum and maximum values prior to shipment.



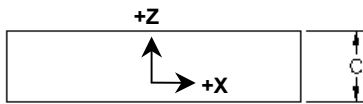
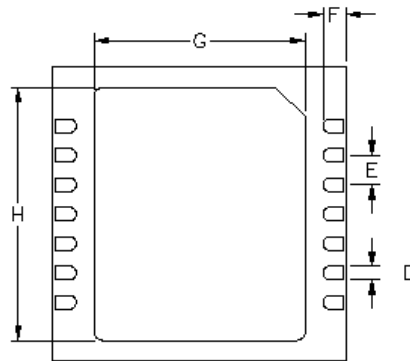
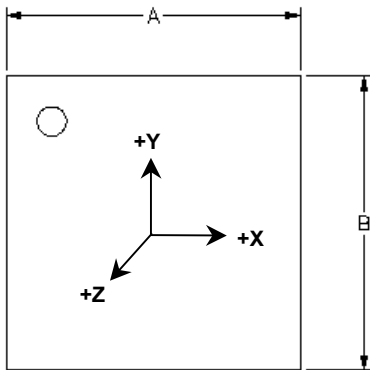
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Package Dimensions and Orientation

5 x 5 x 1.2 mm DFN



| Dimension | mm | | | inch | | |
|-----------|------|------|------|-------|-------|-------|
| | Min | Nom | Max | Min | Nom | Max |
| A | | 5.00 | | | 0.197 | |
| B | | 5.00 | | | 0.197 | |
| C | 1.10 | 1.20 | 1.30 | 0.043 | 0.047 | 0.051 |
| D | 0.18 | 0.23 | 0.28 | 0.007 | 0.009 | 0.011 |
| E | | 0.50 | | | 0.020 | |
| F | 0.35 | 0.40 | 0.45 | 0.014 | 0.016 | 0.018 |
| G | 3.50 | 3.60 | 3.70 | 0.138 | 0.142 | 0.146 |
| H | 4.20 | 4.30 | 4.40 | 0.165 | 0.169 | 0.173 |

All dimensions and tolerances conform to ASME Y14.5M-1994

When device is accelerated in +X, +Y or +Z direction, the corresponding output will increase.

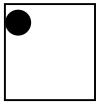
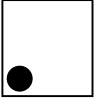
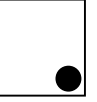
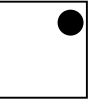
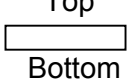
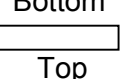


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Static X/Y/Z Output Response versus Orientation to Earth's surface (1g):

| Position | 1 | 2 | 3 | 4 | 5 | 6 |
|------------|---|---|---|--|---|---|
| Diagram |  |  |  |  |  |  |
| X | 1.65 V | 2.31 V | 1.65 V | 0.99 V | 1.65 V | 1.65 V |
| Y | 2.31 V | 1.65 V | 0.99 V | 1.65 V | 1.65 V | 1.65 V |
| Z | 1.65 V | 1.65 V | 1.65 V | 1.65 V | 2.31 V | 0.99 V |
| X-Polarity | 0 | + | 0 | - | 0 | 0 |
| Y-Polarity | + | 0 | - | 0 | 0 | 0 |
| Z-Polarity | 0 | 0 | 0 | 0 | + | - |



Earth's Surface